The secret to building & scaling AV markets

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AV BD Strategist & Accelerator





Collaborative AV Pilots: US Military to Federal to Industry to Consumer



Start Slow...





2011

ARIBO = Living Lab





Army tests driverless vehicles in 'living lab'

BY PATRICK MARSHALL | JUL 16, 2014



Information Classification:













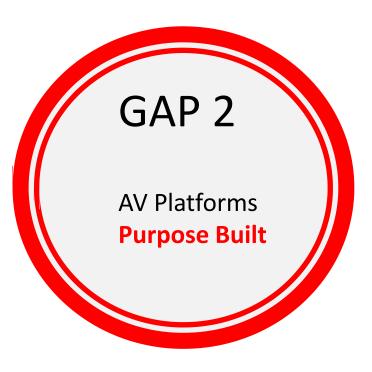












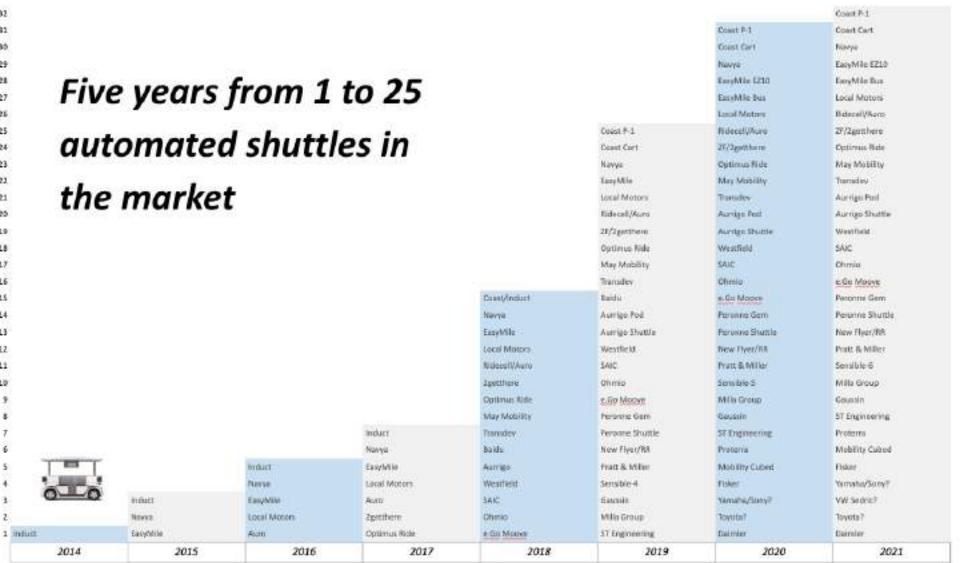




























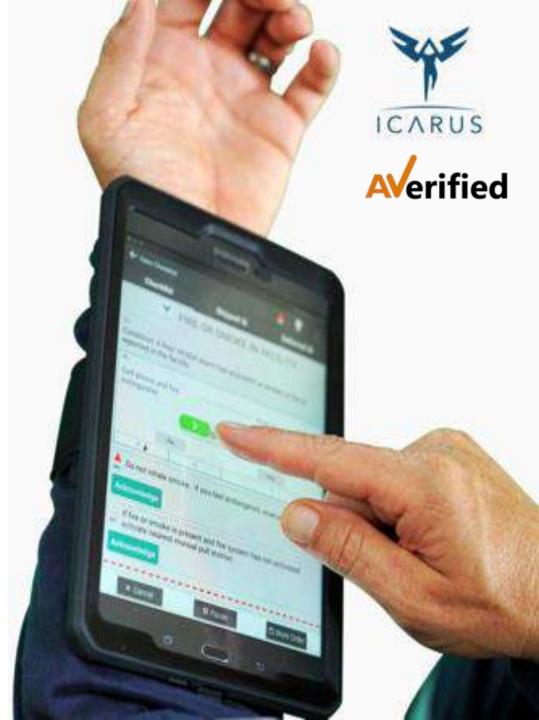


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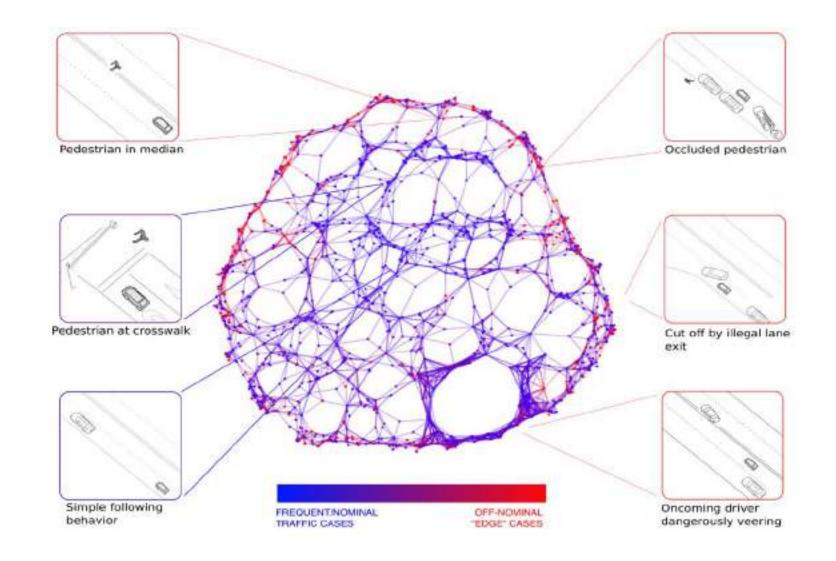
Process Compliance and Verification for AV ops

Digitizing Safety Processes and Procedures





Comprehensive AV testing, training and validation on the world's largest library of edge cases





Identify ODD risks, both general and for specific AVs

dRISK

Risk assessment for a Company A deployment in San Leandro, CA

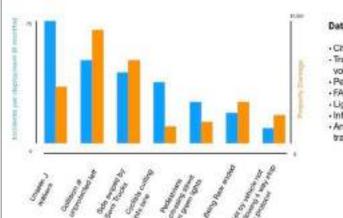
Key Deployment Parameters:

- Vehicles: 10 Chrysler Pacifica Minivans
 Durator: 5 months
- 1 safety driver + 1 systems engineer per vehicle
 Dial-e-ride like service model intended to improve accessibility and mobility
- 95% operational use case is during the day, in non-peak traffic hours, typically traveling between low density residential and commercial areas

The primary risk factors stem from:

- Abundance of non-signalized intersections
 Occlusions from on street parking
- Navigating parking lots
- Trucking comidons and commercial hubs near by
 Unprotected bike lanes along San Leandro Blvd,
 and the CA 185
- Roundabout on Bencroft ave and Victoria ave
 Dead end streets + cul-de-sacs

Risk Contributors





SAMPLE REPORT



Data Sources

 City accident reports
 Trafic flow counts, volume and type data
 Paciestrian counts
 PARS database
 Light Cycle data
 Infrastructural apecs
 Analysis of xideo from trafic-comeras



es to train AV stack with in simulation

SAMPLE REPORT

ge case archetypes Company A has performed, from previous compared to new edge cases present in San Leandro, CA.

Edge Lates Company A

are present in San Leandra

Cases 5 vehicle edge cases.

has not takened with which

Primary Gap in Deployment Readiness

- Company A has collected several scenarios/edge cases for training their stack
- the not around deployed around industrial heavy commercial areas
- Geo locked area is near logistical hubs
 This area sees an influx of class 8 vehicles, expecially during non peak traffic hours
- Largest gap in readiness is from edge cases, where the AV is in the path of a class 8 which turning at intersactions and being in their blind spots
 Company A had to train their AV stack on the following edge case andhetypes and several iterations of them.

A tractor trailer is trying to make a left turn at an intersection, has miscompensated and the trailer is now in a direct collision path with the AV.

Iterations of this scenario was used to train the AV stack in order for it to avoid this scenario archetype.









Scale AV Deployment and Build Trust:

- Education
- Analysis & Shared Data
- Planning
- Collaboration
- Smart City Integration
- Demo to Pilot to Deployment

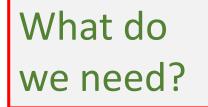




Trust

Are we ready to YES. scale low-speed applications?

What do we need?



More AV Options Purpose Built AVs (production-level) Comparable Pricing Safety Verification More Pilots to Deployments More Collaboration More Ops Data Sharing



Mobility Innovation Team

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Corey's Lessons Learned

Riders Rule Media Often Gets it Wrong

Under Promise

Test & Re-Test

Gotta Have a Business Case

Team Inductive Charging

Share Data

There Are Amazing People in AV World

Keep Going

...Let's Build EPCOT

Plan for Accidents

